Antonio Guillen-Perez

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Dedicated AI research scientist with a Ph.D. in computer science, bringing over 5 years of experience in deep reinforcement learning (DRL), autonomous vehicles, and sustainability. Expert in applying DRL to multi-agent coordination, with a track record of significant contributions to major AI conferences (NeurIPS, CVPR, AAAI) and leading IEEE journals. Committed to pushing the boundaries of AI research and its application in real-world challenges.

EXPERIENCE

Hewlett-Packard Enterprise (HPE) - AI Labs

Milpitas-San Jose, CA Sep 2022 - Now

- Research Scientist
 - Led Multi-Agent Deep Reinforcement Learning (MADRL) research projects projects for sustainable computing, focusing on data center energy optimization, workload shifting, and carbon footprint reduction.
 - Develop **AI-based cooling solutions** and Computational Fluid Dynamics (CFD) surrogate models for energy efficiency, integrating MADRL and **genetics algorithms** for real-time optimization.
 - Research on **bayesian optimization** and **model robustness**, contributing to AI's reliability and efficiency.

Polytechnic University of Cartagena

Associate Lecturer

- Taught theoretical and practical classes in communication network theory and distributed systems and services, with emphasis on network optimization and distributed services performance.
- Conducted research on network optimization algorithms and applied distributed techniques in academic applications.

Dolphin Wave — Startup

ML Engineer and Data Scientist

- Applied ML models (XGBoost, LightBGM, and Neural Networks) for urban mobility studies, utilizing WiFi & BLE RSSI signals @ 2.4 and 5GHz for precise environmental positioning and sensing.
- Utilized FB Prophet, ARIMA, and LSTM networks for Multimodal Time Series Forecasting in demand prediction, thereby enriching business intelligence tools.

Polytechnic University of Cartagena

Research Intern in the Department of Information and Communications Technologies

- Developed an intelligent traffic light control system using **DRL**, improving urban traffic management.
- Researched and applied generative models for security and optimization in urban settings, enhancing intelligent system capabilities.

EDUCATION

Polytechnic University of Cartagena

Ph.D. in Computer Science, Autonomous Vehicles, and Wireless Communications; CUM LAUDE. Sep 2018 - Jun 2022

- Thesis: "Contribution to Enhancing the Cognitive Capability of Intelligent Transportation Systems (ITS) Using Artificial Intelligence". Link: doi:10.31428/10317/11206.
- Key focus on AI and **DRL** for improving urban traffic management and **Connected Autonomous Vehicles** (CAVs).
- Achieved significant reductions in waiting times (56%) and carbon emissions ($\approx 45\%$) at traffic intersections.
- Engaged in interdisciplinary research, integrating 5G/6G mobile network for CAVs, and explored Learning-from-Demonstrations to accelerate **MADRL** training $(\times 5)$.

University of California, Davis

- Predoctoral Stay Researcher Visitor
 - Focused on AI in healthcare, specifically early detection of throat cancer, achieving over 90% accuracy. Pioneered a new research direction for disease detection using multimodal neural networks. Nature Paper Link

Polytechnic University of Cartagena

Master and Bachelor's Degree in Electrical, Electronic, and Communications Engineering

• Specialized in Communications Systems and Wireless Networks. Conducted comprehensive studies on UAV network performance and developed a wireless sensor network for environmental monitoring.

Cartagena, Spain Sep 2018 - Jun 2022

Murcia, Spain

Feb 2018 - Sep 2018

Cartagena, Spain Sep 2014 - Sep 2018

Cartagena, Spain

Davis, CA Jun 2021 - Jan 2022

Cartagena, Spain

Sep 2012 - Sep 2018

JOURNAL ARTICLES

- Guillen-Perez, A., & Cano, M.-D., "Multi-Agent Deep Reinforcement Learning to Manage Connected Autonomous Vehicles at Tomorrow's Intersections," *IEEE Transactions on Vehicular Technology*, vol. 71, no. 7, pp. 7033-7043, 2022. doi:10.1109/TVT.2022.3169907.
- Guillen-Perez, A., & Cano, M.-D., "Learning from Oracle Demonstrations (LfOD) A new approach to develop AIM control algorithms based on MADRL," *IEEE Access*, vol. 10, pp. 53601-53613, 2022. doi:10.1109/ACCESS.2022.3175493.
- Guillen-Perez, A., et al., "Flying Ad Hoc Networks: A New Domain for UAV Network Communications." Sensors, vol. 18, no. 10, article 3571, 2018. doi:10.3390/s18103571.

Conference Proceedings

- Naug, A.*, Guillen-Perez, A.*, et al., "Concurrent Carbon Footprint Reduction (C2FR) Reinforcement Learning Approach for Sustainable Data Center Digital Twin," 2023 IEEE 19th International Conference on Automation Science and Engineering (CASE), pp. 1-8, 2023. doi:10.1109/CASE56687.2023.10260633.
- Guillen-Perez, A., et al., "WiFi Networks on Drones," 2016 ITU Kaleidoscope: ICTs for a Sustainable World (ITU WT), pp. 1-8, 2016. doi:10.1109/ITU-WT.2016.7805730.

WORKSHOPS

- Naug, A.*, Guillen-Perez, A.*, et al., "Real-time Carbon Footprint Minimization in Sustainable Data Centers with Deep Reinforcement Learning," *NeurIPS 2023 Workshop on Tackling Climate Change with Machine Learning*, 2023. Link. Award: Best ML Innovation. Award Link.
- Naug, A.*, Gutierrez, R.-L.*, Guillen-Perez, A.*, et al, "Sustainable Data Center Modeling: A Multi-Agent Reinforcement Learning Benchmark," *NeurIPS 2023 Workshop on Tackling Climate Change with ML*, 2023. Link.

Skills

- Programming & Development: Expert in Python; proficient in Java, Matlab, and Jupyter Notebook. Skilled in Git for version control, along with practical experience in Docker for containerization and familiarity with cloud platforms like AWS and Google Cloud.
- Artificial Intelligence & Machine Learning: Experienced with PyTorch and TensorFlow for AI model research and development. Proficient in DRL using RLLib, RAY, and OpenAI Gym.
- Computational Modeling & Simulation: Proficient with CFD tools (6SigmaDCX) for thermal and energy modeling, and knowledgeable in FMU/FMI and Modelica for physical system simulations.
- Collaboration & Communication: Effective collaborator within interdisciplinary teams, with a strong grasp of IATEX for documentation and the Adobe Suite for creating visuals. Demonstrated proficiency in conveying complex concepts clearly and effectively.

Advanced Coursework and Specializations

VIEW MORE ON LINKEDIN

- Deep Reinforcement Learning: Focused studies in cutting-edge techniques and applications, including:
 - Deep Reinforcement Learning Nanodegree (Udacity) Comprehensive coverage of advanced DRL algorithms and their practical applications.
 - Practical Reinforcement Learning (Coursera) Hands-on experience with DRL techniques and frameworks.
- Autonomous Vehicle Systems: Completion of the Self-Driving Cars Specialization (Coursera, University of Toronto), encompassing:
 - Introduction to Self-Driving Cars Foundations of autonomous vehicles. Hands-on experience with CARLA simulator.
 - State Estimation and Localization Techniques for accurate vehicle positioning.
 - Visual Perception for Self-Driving Cars Implementing computer vision and sensor fusion.
 - Motion Planning for Self-Driving Cars Strategies for dynamic path planning and decision-making.
- Natural Language Processing: Key courses on NLP, focusing on modern techniques and models, including:
 - Natural Language Processing with Attention Models (Coursera) Part of Natural Language Processing Specialization from DeepLearning.AI. Comprehensive exploration of attention mechanisms and their application in NLP.
- Generative AI: Foundational and advanced topics in generative models, including:
 - How Diffusion Models Work (DeepLearning.AI) Exploring the cutting-edge world of diffusion-based generative AI.
 - Introduction to Generative AI (Coursera) A primer on generative AI technologies and their practical applications.

References

- Prof. J. Sebastian Gomez-Diaz • Professor and MS Program Director, Electrical and Computer Eng.
- Prof. Maria Dolores Cano Banos

Professor and Lead Researcher, R&D Group in AI and Networking

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Polytechnic University of Cartagena (UPCT), Spain Email: mdolores.cano@upct.es